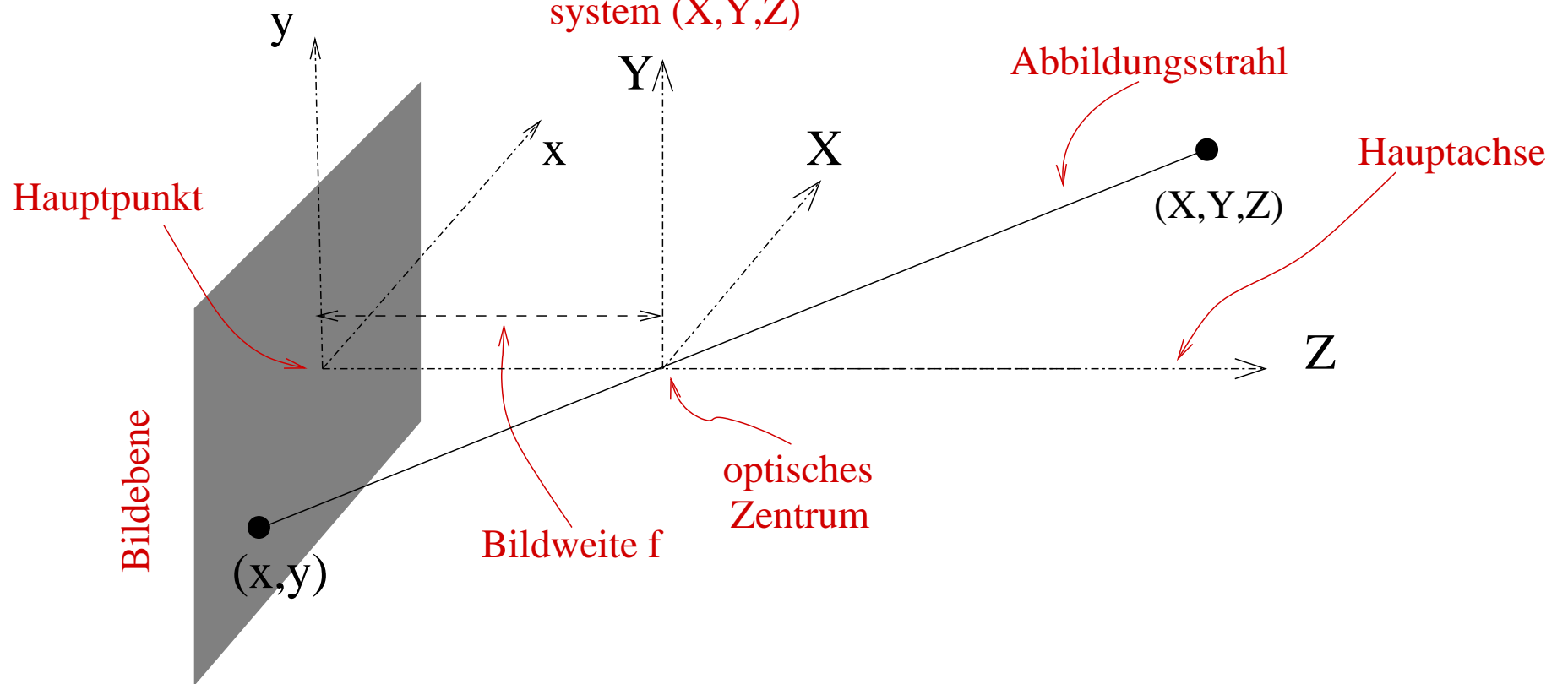
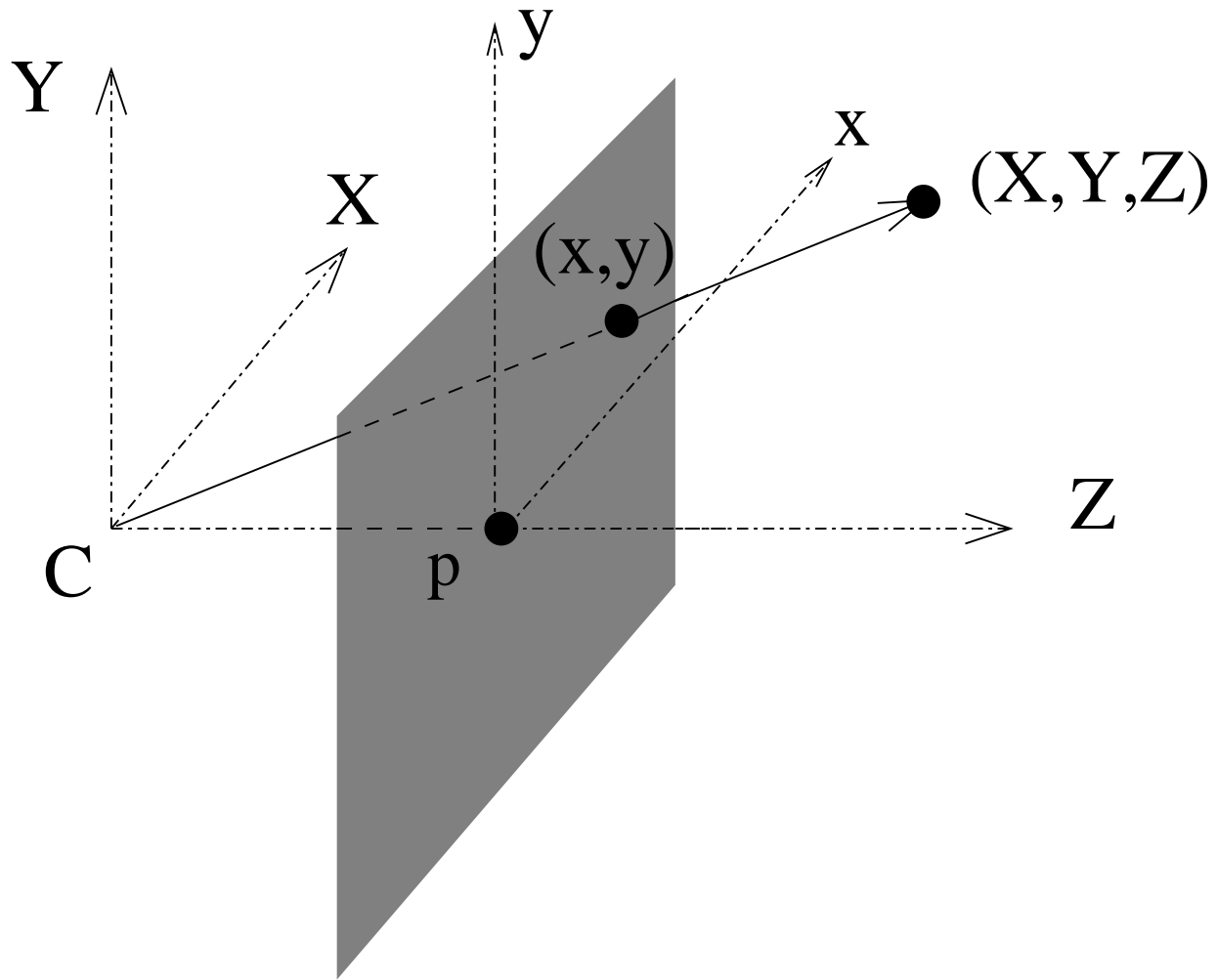
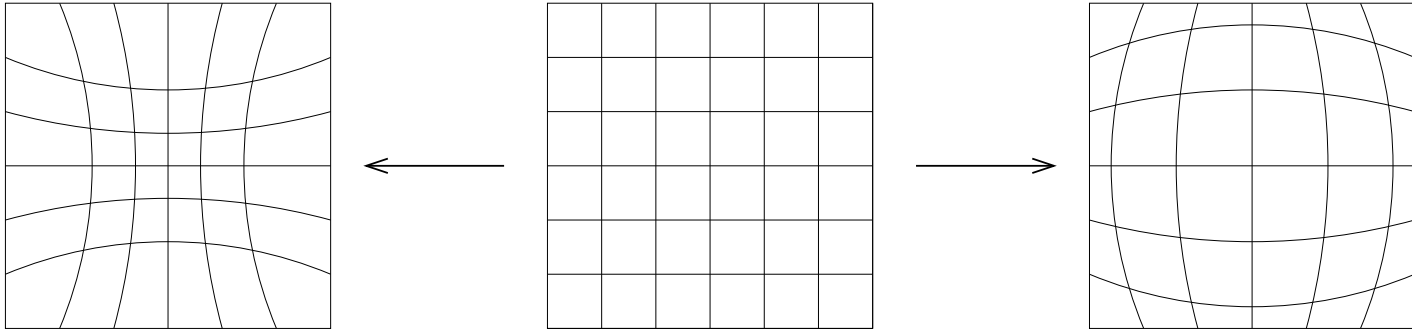


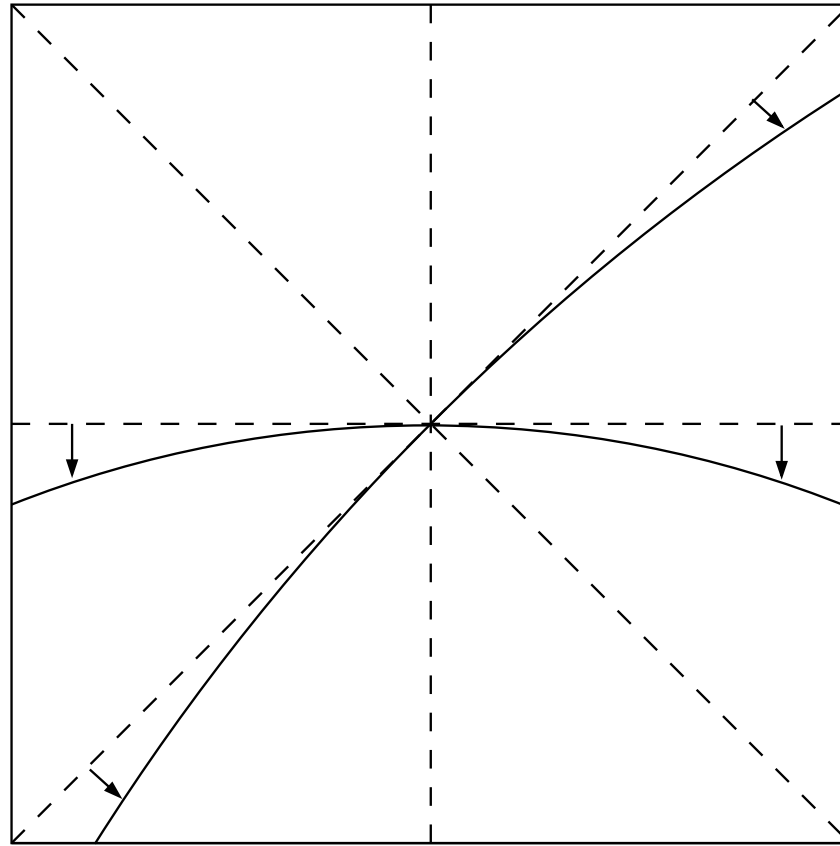
Bildkoordinatensystem  $(x,y)$

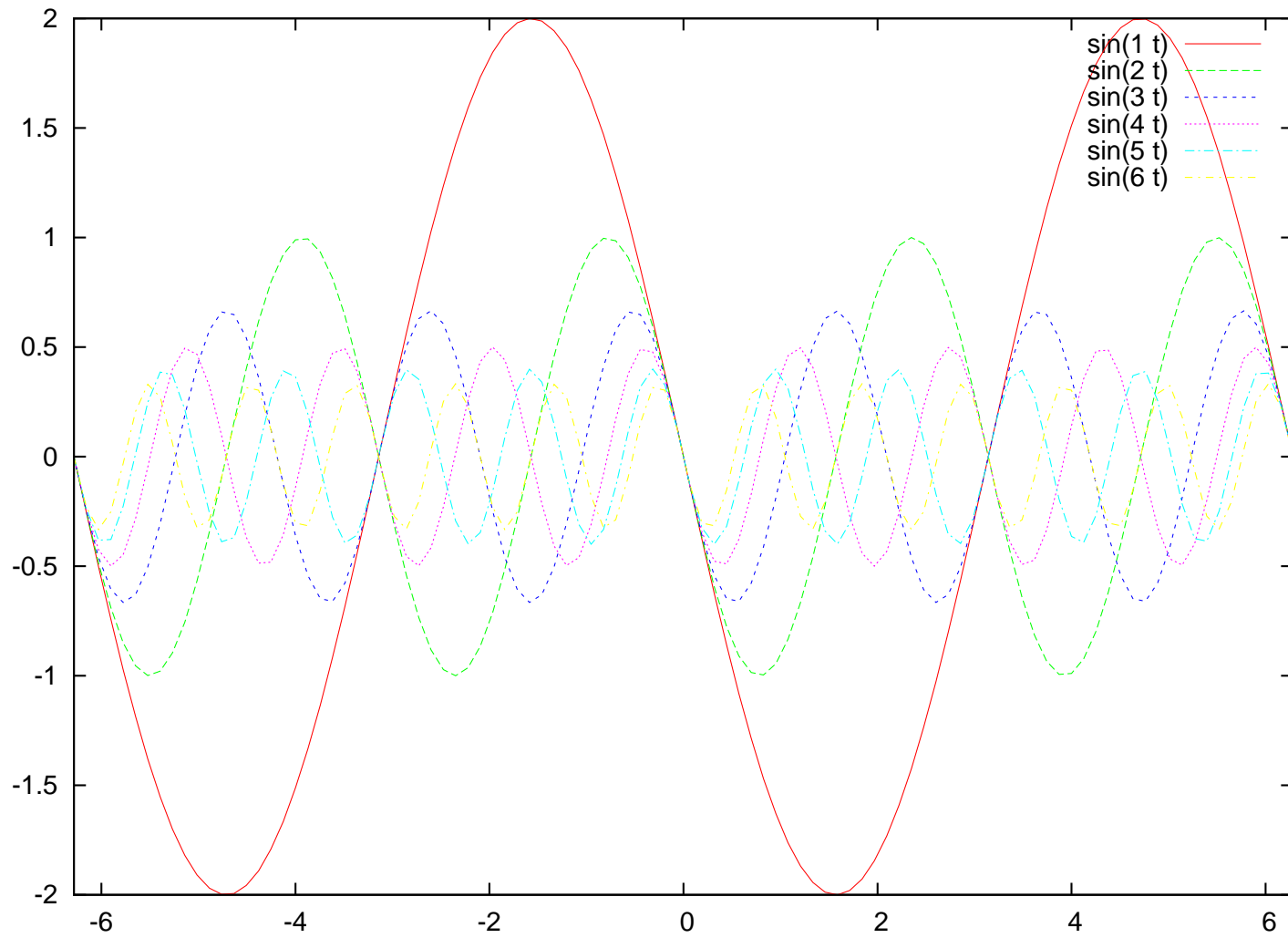
Kamerakoordinatensystem  $(X,Y,Z)$

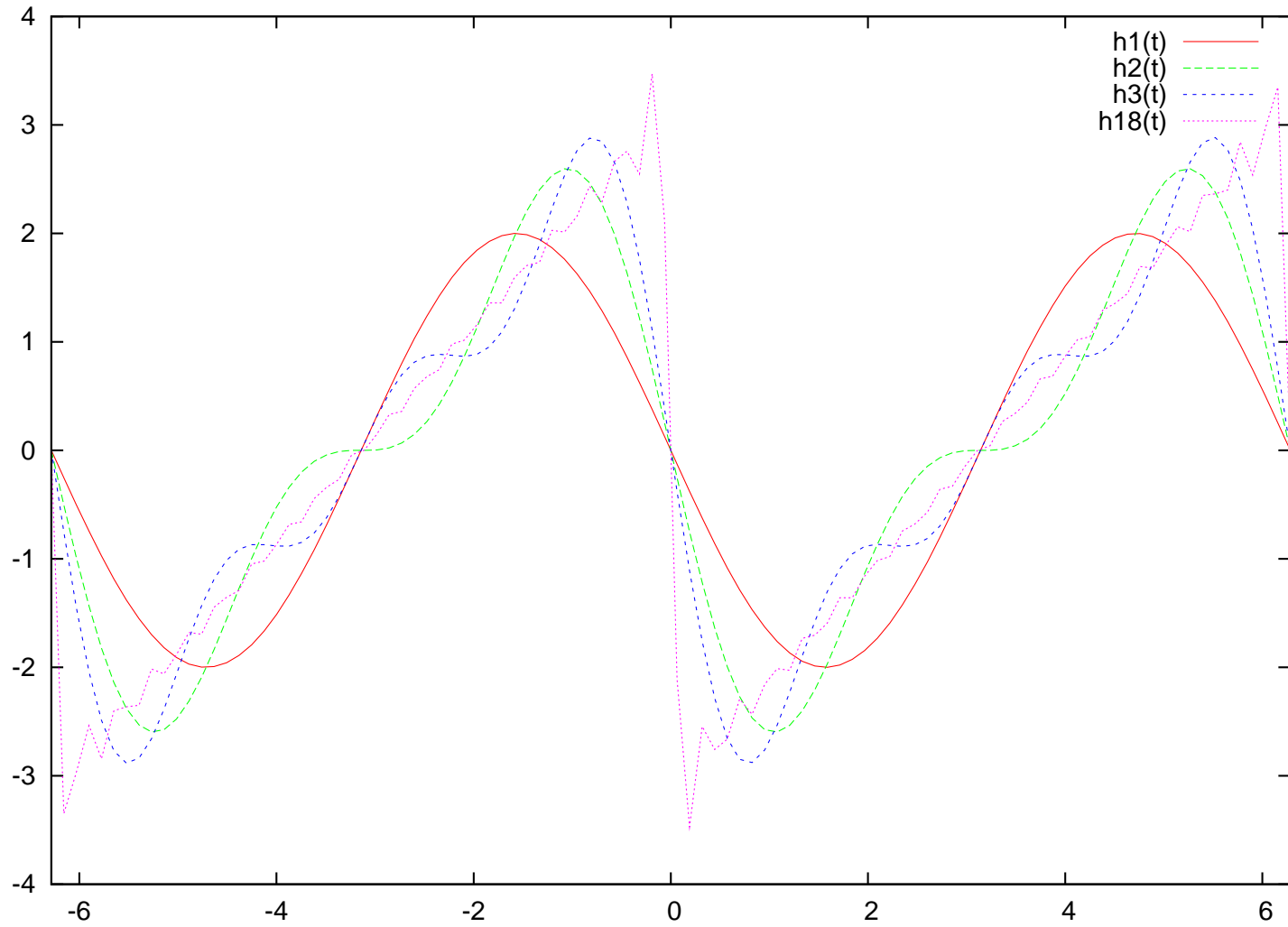


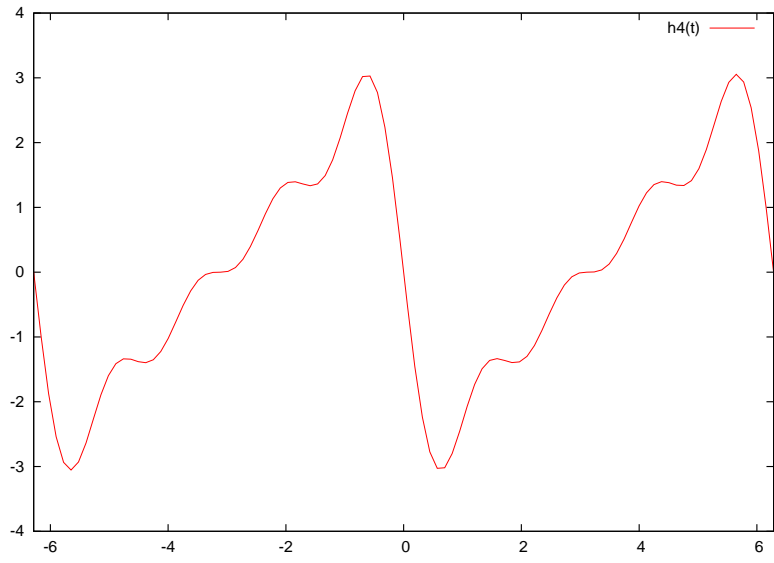
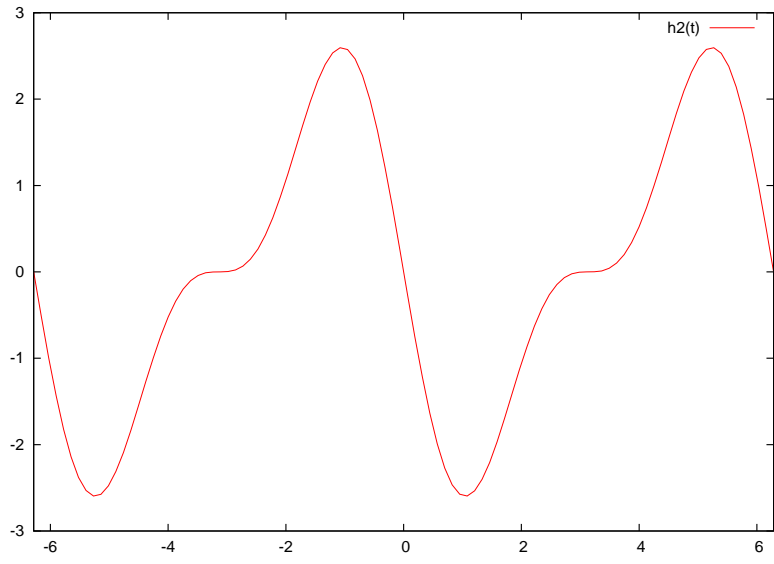
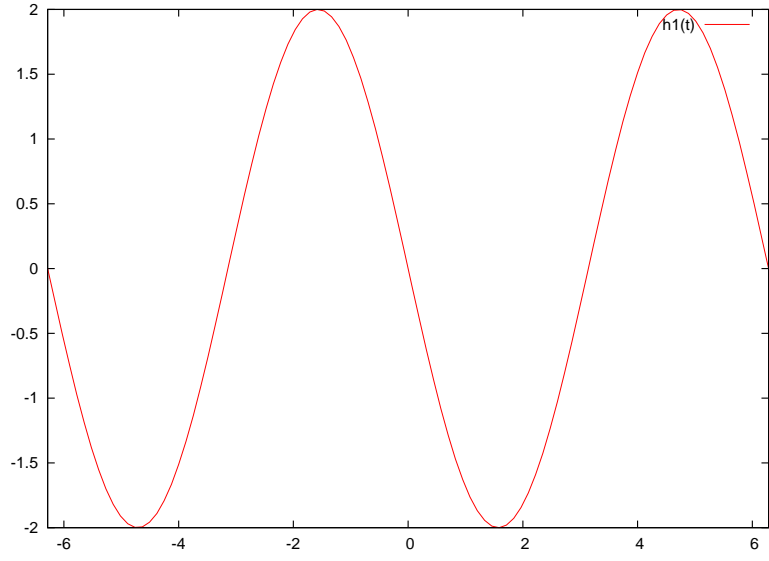


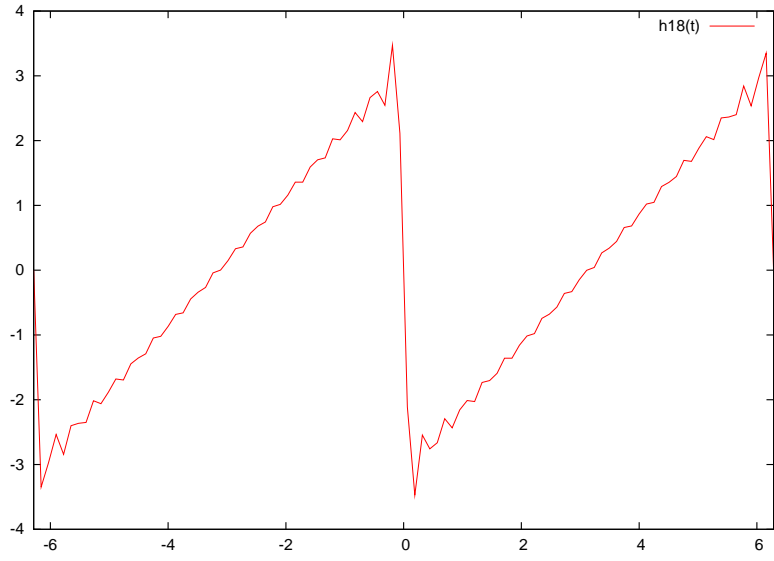
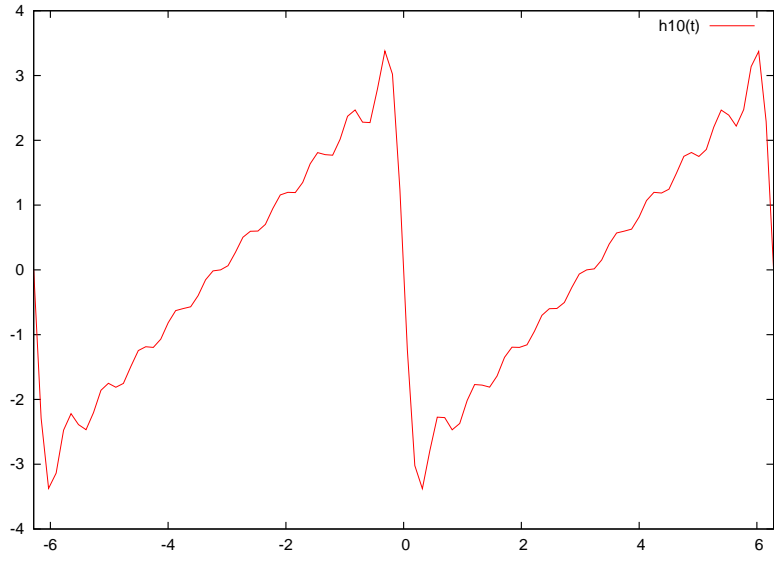
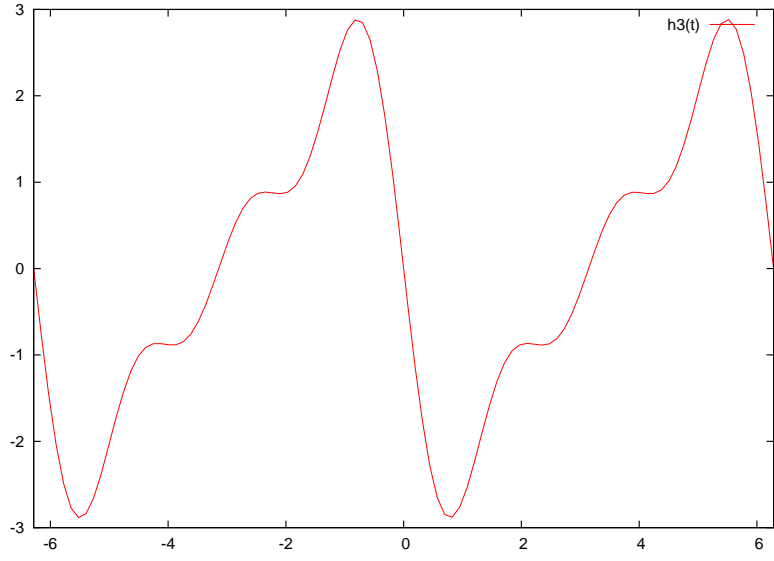




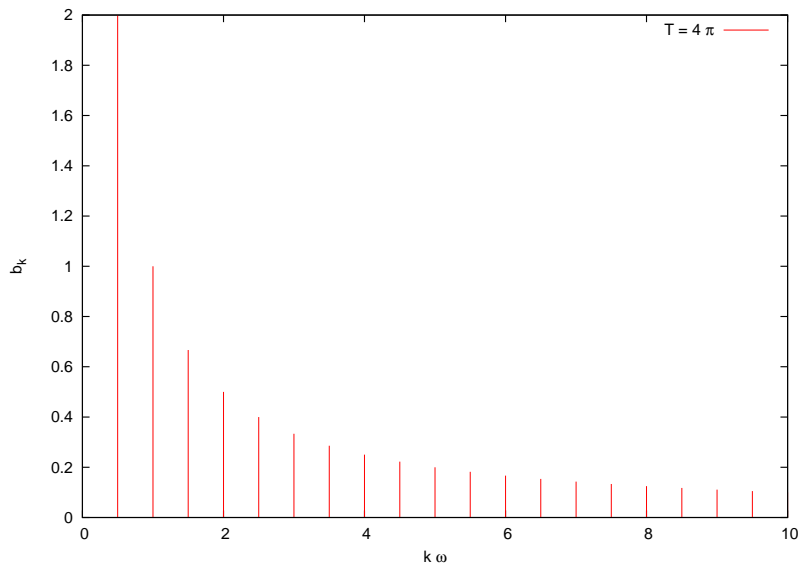
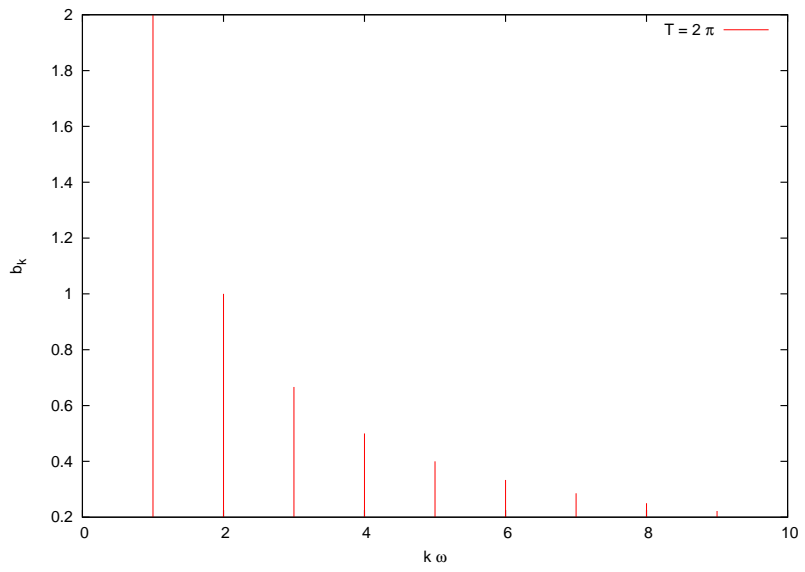
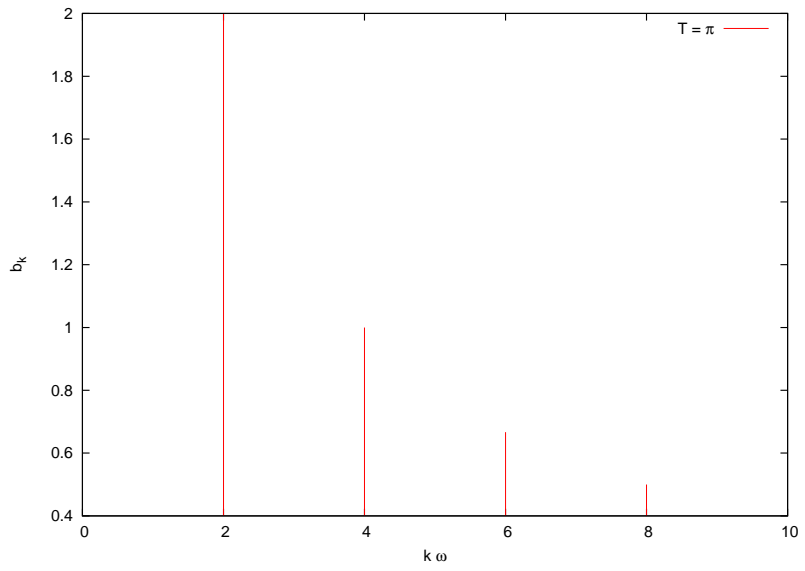


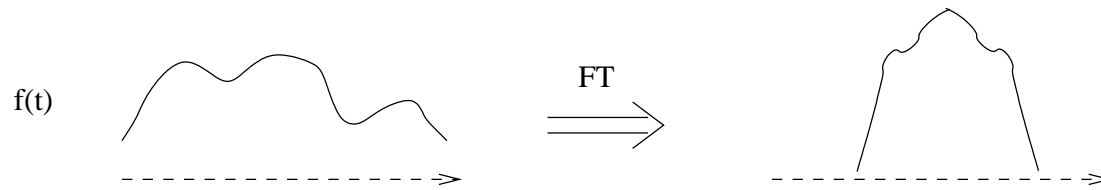




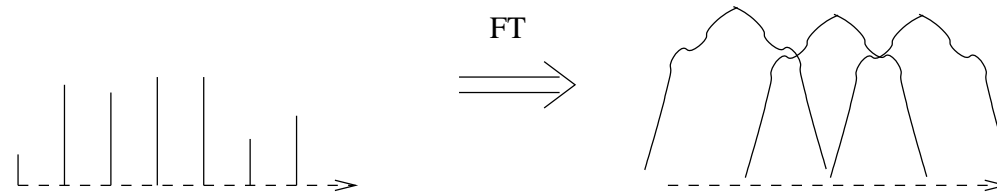
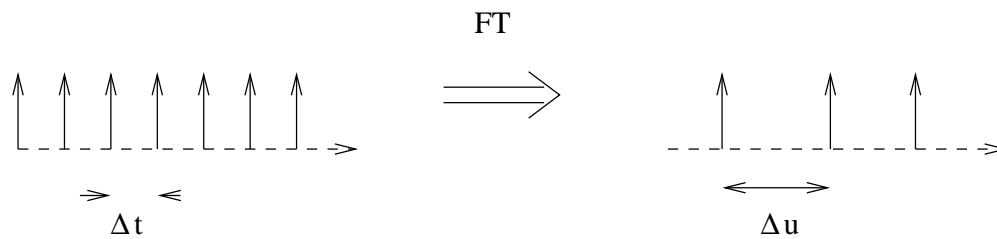








$\delta$ -Kamm



die einzelnen Kopien werden aufsummiert